

## فهرست الگوریتم‌ها

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```
DBSCAN (D, eps, MinPts) {  
   $C = 0$  for each point P in dataset D {  
    if P is visited  
      continue next point  
    mark P is visited  
    NieghborPts = regionQuery (P, eps)  
    if sizeof (NieghborPts) < MinPts  
      else {  
         $C = \text{next cluster}$   
        expandCluster (P, NieghborPts,  $C$ , eps, MinPts)  
      }  
    }  
  }  
}
```

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